Combinatorial Mathematics

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Outline

- The Maximum Matching Problem
 - A Generic Algorithm and the Berge's Theorem
 - The Augmenting Path Problem in Bipartite Graphs
 - A simple DFS-like recursive algorithm
- Concluding Notes
 - The best algorithms for Maximum Matching

The Maximum Matching Problem

To compute a maximum-size matching for the input graph.

The maximum matching problem

- Input :
 - A graph G = (V, E).
- Output :
 - A matching $M \subseteq E$ that has the maximum size among all possible matchings.

Maximal matching v.s. Maximum matching

A matching M is called maximal,
 if there exists no other matching M' that contains M.

A matching *M* is called maximum,
 if its size is at least the size of all other matchings.



A maximal matching

A maximum matching

■ Note that,

a maximal matching is not necessarily a maximum matching.

Local maximum vs global maximum

How Can We Enlarge the Size of a Matching?

- To enlarge the size of a matching, we can add edges to the current matching until it becomes maximal.
- However,

a maximal matching is not necessarily a maximum matching.

• What can we do?



Alternating Path & Augmenting Path

■ Given a matching *M*,



- an *M*-alternating path is a path
 that alternates between edges in *M* and edges not in *M*.
- an *M*-augmenting path is an *M*-alternating path that both starts and ends at unmatched vertices.

 $v_1, v_2, v_3, v_4, v_5, v_6$ is an *M*-augmenting paths.

 v_1, v_2, v_3 and v_2, v_3, v_4, v_5 are both *M*-alternating paths.

Observation



■ We can see that,

each *M*-augmenting path *P* is a way to enlarge the size of *M* by 1.

- This is done by swapping the status of the edges on the path.
 - Matched edges \Rightarrow unmatched
 - Unmatched edges \Rightarrow matched





Observation



We can see that,

each *M*-augmenting path *P* is a way to enlarge the size of *M* by 1.

• $M' \coloneqq (M \setminus P) \cup (P \setminus M)$ is a valid matching with |M'| = |M| + 1.

A simple greedy algorithm

The observation suggests the following algorithm.

- Let G = (V, E) be the input graph.

- 1. $M \leftarrow \emptyset$.
- 2. Repeat until there is no *M*-augmenting path in *G*.
 - a. Find an *M*-augmenting path *P*.
 - b. Set $M \leftarrow (M \setminus P) \cup (P \setminus M)$.
- 3. Output *M*.

1. $M \leftarrow \emptyset$.

2. Repeat until there is no *M*-augmenting path in *G*.

- a. Find an *M*-augmenting path *P*.
- b. Set $M \leftarrow (M \setminus P) \cup (P \setminus M)$.

3. Output *M*.

The philosophy behind the algorithm is very simple :

"Make the current matching larger until no augmenting path exists."

A very natural question is that,

"Does it always output the maximum matching?"

Theorem 1. (Berge 1957).

A matching *M* in a graph *G* is a maximum matching if and only if *G* has no *M*-augmenting path.

Theorem 1 assures the correctness of the previous algorithm.

"Yes, the algorithm always outputs a maximum matching for G."

■ The next question is,

"is the algorithm efficient?"

That is, can we *efficiently* <u>determine</u> <u>the existence</u> of augmenting paths and <u>compute one</u> if it exists?

We will address this problem later.

Symmetric Difference

- Let G = (V, E) be a graph, and $A, B \subseteq E$ be two edge sets.
 - The symmetric difference of A and B is defined as

 $A \bigtriangleup B \coloneqq (A \setminus B) \cup (B \setminus A).$

- That is, the set of edges that appear exactly once in A and B.

Lemma 2.

Let M, M' be two matchings for a graph G.

Every component of $M \bigtriangleup M'$ is a path or a cycle with an even length.

• Let $F \coloneqq M \bigtriangleup M'$.

- Each vertex in G is incident to at most two edges in F.
- Hence, each component in *F* is either a path or a cycle.
- Consider any cycle in *F*.
 - The cycle alternates between edges in M and M'.
 - It must have an even length.



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 $M \bigtriangleup M$

Theorem 1. (Berge 1957).

A matching *M* in a graph *G* is a maximum matching if and only if *G* has no *M*-augmenting path.

- Let us prove Theorem 1.
 - The direction \Rightarrow is clear.
 - It suffices to prove that,

if *G* has no *M*-augmenting path, then *M* is a maximum matching.

We will prove the contrapositive of the above, i.e.,

if M' is a matching with |M'| > |M|,

then *G* has an *M*-augmenting path.

It suffices to prove that, if M' is a matching with |M'| > |M|, then *G* has an *M*-augmenting path.

- Let $F \coloneqq M \bigtriangleup M'$.
 - By Lemma 2, F is a union of paths and even cycles.
- Since |M'| > |M|,

there must be a component in F that has more edges from M' than M.

- The component must be a path.
 Furthermore, it must start and ends with edges in M'.
- The path is then an *M*-augmenting path.

The Augmenting Path Problem

in Bipartite Graphs

The augmenting path problem in bipartite graphs can be solved by DFS in O(n + m) time!

The Augmenting Path Problem in Bipartite Graphs

Input :

- A bipartite graph G = (V, E) and a matching M for G.
- Goal :
 - An *M*-augmenting path for *G*, or asserts that there exists no such paths.

• We will present an O(n + m) algorithm for this problem.

This leads to an O(nm) algorithm for the maximum bipartite matching problem.

A Simple DFS-like Algorithm

- Finding an *M*-augment path problem in a bipartite graph can be done by a simple & intuitive DFS-like algorithm.
 - We start with an unmatched vertex, say, *u*.
 - The goal is to find an M-augmenting path starting from u.
 - Consider each neighbor of u, say, v.



If v is <u>unmatched</u>, then u, v is an *M*-augmenting path, and we're done.

- We start with an unmatched vertex, say, *u*.
 - Our goal is to find an *M*-augmenting path starting from *u*.
- Consider each neighbor of u, say, v.



Then, the goal becomes finding an *M*-augmenting path *starting from u*'.

If v is *matched*, then

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to form an *M*-augmenting path that passes v, we must follow the matched edge to some u'.

This is a recursive problem that starts at the vertex u'.

- We start with an unmatched vertex, say, *u*.
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U

Then, the goal becomes finding an *M*-augmenting path *starting from u*'.

This is a recursive problem starting at the vertex u'.

If it fails, we go back to u, and continue to examine the next neighbor until all its neighbors have been examined.

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The DFS-like Recursive Algorithm

- To describe the algorithm, let's assume the following.
- The graph is represented by adjacency lists.
- For each vertex v,

let match[v] denote the vertex to which v is matched.

- match[v] = -1 if v is unmatched.

The DFS-like recursive algorithm goes as follows.

<u>Procedure</u> Aug-Path(u)

- 1. Mark *u* as *visited*.
- 2. For each neighbor v of u, do.
 - If v is unmatched, or,

if match[v] is *unvisited* and Aug-Path(match[v]) is true, then

- a. Set match[u] = v and match[v] = u. // match u with v
- b. Return true.
- 3. Return false.



The Augmenting Path Algorithm

for Bipartite Graphs

The Augmenting Path Algorithm for Bipartite Graphs

- Let G = (V, E) be the input bipartite graph and M a matching for G.
- The algorithm goes as follows.

The Augmenting Path Algorithm (for Bipartite Graphs).

- 1. Mark all the vertices as *unvisited*.
- 2. For each *unmatched* vertex, say, u, do
 - If Aug-Path(u) returns true, then report "Yes."
- 3. Report "No."

The Augmenting Path Algorithm for Bipartite Graphs

- Since each vertex is visited at most once and each edge is examined at most twice by the procedure Aug-Path(),
 - The algorithm runs in O(n+m) time.
- It is clear that, if Aug-Path(u) returns true,
 then an *M*-augmenting path starting at u is found.
- To prove the correctness of the algorithm, it remains to prove that,
 - There exists no *M*-augmenting path in the graph when the algorithm reports "No."

The Augmenting Path Algorithm for Bipartite Graphs

- To prove the correctness of the algorithm, it remains to prove that,
 - There exists no *M*-augmenting path in the graph when the algorithm reports "No."

 We will prove that, if the algorithm reports "No," then G has a vertex cover C of size |M|.

It takes at least one vertex to cover each edge in *M*.

- Since $|C| \ge |M'|$ holds for all matching M' for G, this will imply that M is a maximum matching for G.

Some Notations

• Let A and B be the two partite sets of G.

- Let *U* be the set of unmatched vertices in *A*.
- Let *S* be the vertices in *A* that are marked as *visited*.
- Let T be the set of vertices in B that are matched to $S \setminus U$ by M.





Theorem 3.

If the Augmenting Path Algorithm reports "No," then the set $C \coloneqq (A \setminus S) \cup T$ is a vertex cover for *G* with size *M*.

Note that, this is also a *constructive proof* for the König-Egeváry theorem.

Observation 1.

Since v is marked visited, it is visited by a recursion call that originates from some $u \in U$.

- For each $v \in S$,
 - There is an *M*-alternating path that starts at some $u \in U$ and ends at v with a matched edge in *M*.



Observation 2.

• There exists no edge between S and $B \setminus T$.

- By the way S is defined, there exists no edge between S and the matched vertices in B.
- If there exists an edge between S and some unmatched vertex in B,
 it will be an augmenting path.



A contradiction since the algorithm reports "No."

If so, that matched vertex should be classified in *T*.

Theorem 3.

If the Augmenting Path Algorithm reports "No," then the set $C := (A \setminus S) \cup T$ is a vertex cover for *G* with size *M*.

- The edges between S and T can be covered by T.
- By Observation 2, the remaining edges can be covered by $A \setminus S$.
- Hence, C is a vertex cover for G.



Concluding Notes

Best Algorithm for the Maximum Bipartite Matching

In this lecture,

we have seen an $O(nm) = O(n^3)$ algorithm for this problem.

The best algorithm for this problem is the Hopcroft-Karp algorithm, which runs in $O(\sqrt{n}m) = O(n^{2.5})$.

The Hopcroft-Karp Algorithm

- The best algorithm for this problem is the Hopcroft-Karp algorithm, which runs in $O(\sqrt{n}m) = O(n^{2.5})$.
 - The idea is to perform a *BFS* simultaneously from all unmatched vertices in one partite set to form alternating layers until some unmatched vertices in the other partite set is met.
 - Then a *layer-guided DFS* is used to construct a maximal set of <u>vertex-disjoint shortest augmenting paths</u>.
 - It is guaranteed that, only $O(\sqrt{n})$ rounds are needed before the maximum matching is computed.

Maximum Matching in General Graphs

- For general graphs, a maximum matching can be computed by Edmonds Blossom algorithm in $O(n^2m) = O(n^4)$ time.
 - It is a beautiful algorithm.
- The best (and more complicated) algorithm, due to Micali and Vazirani, solves this problem in $O(\sqrt{n}m) = O(n^{2.5})$ time.